

# Physics dependent de-featuring. Is it a prerequisite for mesh generation?

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**Tetrahedron V**  
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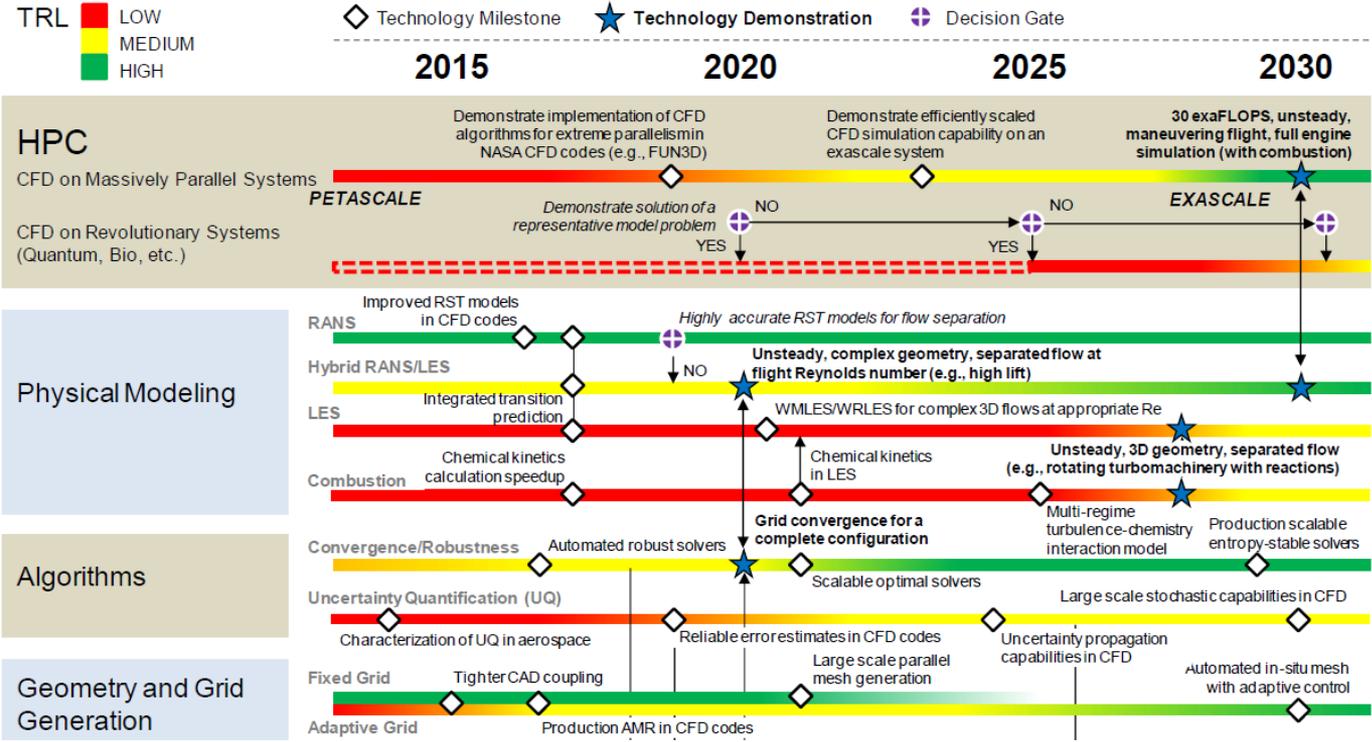
# Outline

1. Motivation
2. NURBS-Enhanced FEM (NEFEM)
3. Mesh generation for NEFEM
4. Examples
5. Concluding remarks

# Motivation

## NASA CFD vision 2030

- Emphasis on **transient** phenomena and complex geometries and tighter coupling of design (CAD) and simulations

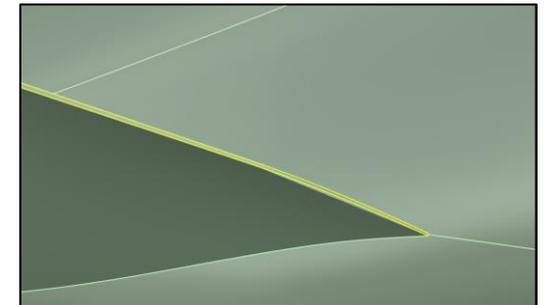
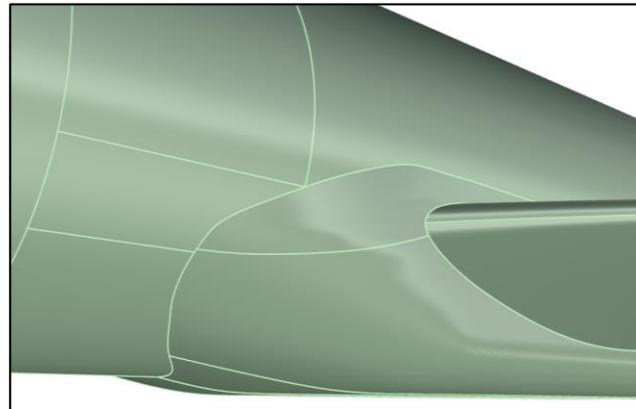
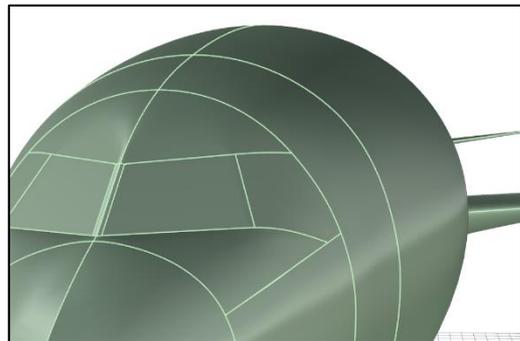
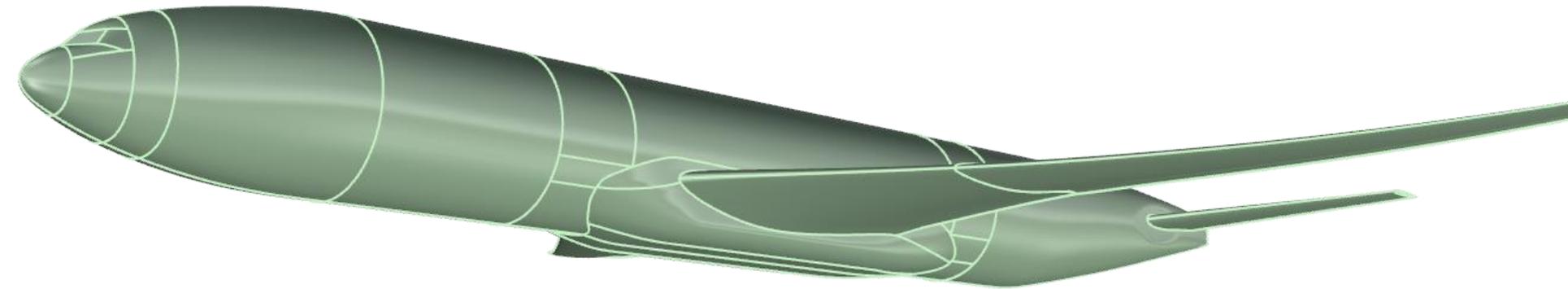


*“Today, the generation of suitable meshes for CFD simulations about complex configurations constitutes a principal bottleneck in the simulation workflow process.”*

*“Many existing CAD geometry definitions are poorly suited for CFD analyses due to excessive detail.”*

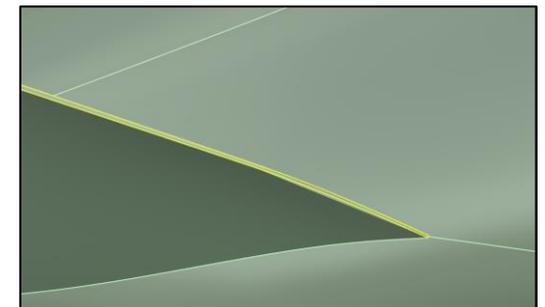
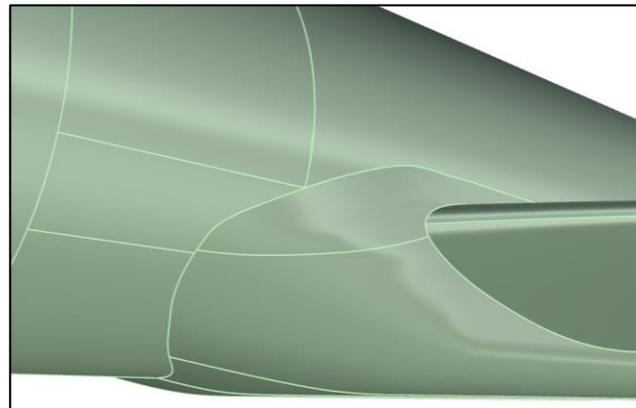
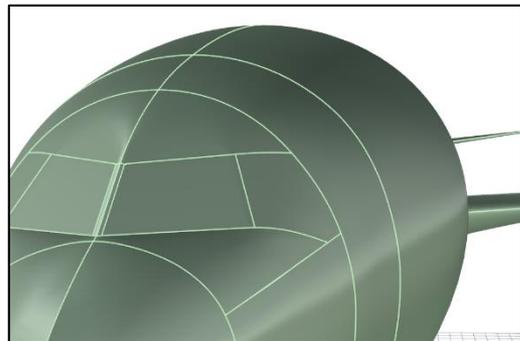
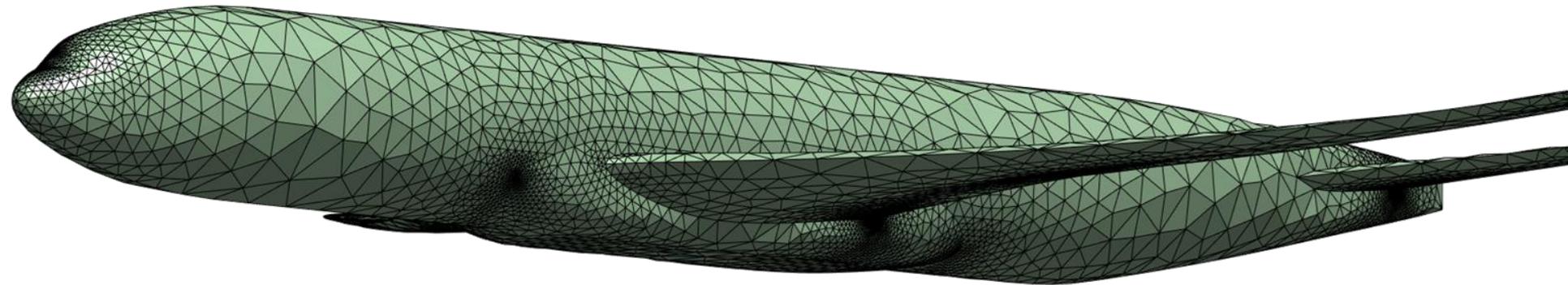
# Motivation

- **Generation of suitable FE meshes from CAD models**
  - The preparation of CAD models for mesh generation is still the major bottleneck in finite element simulations within industry
  - Cleaning and de-featuring takes **80% to 90%** of the time invested in performing a simulation



# Motivation

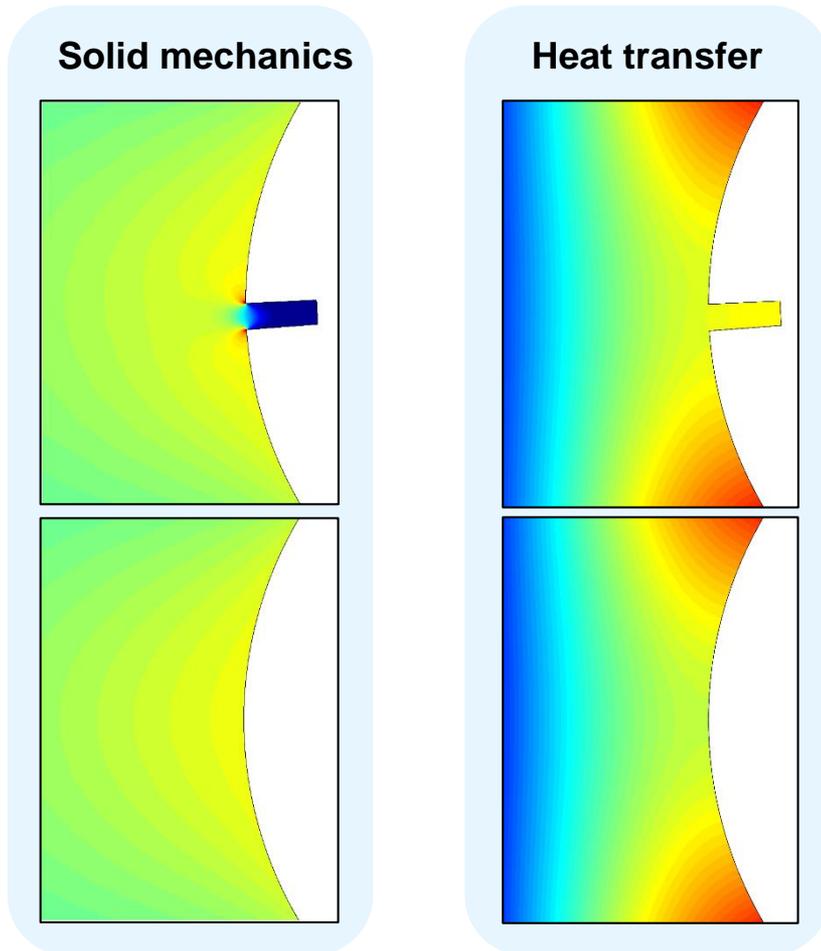
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# Motivation

## ■ De-featuring

- A major drawback of the de-featuring is that is **dependent on the physics** of the problem

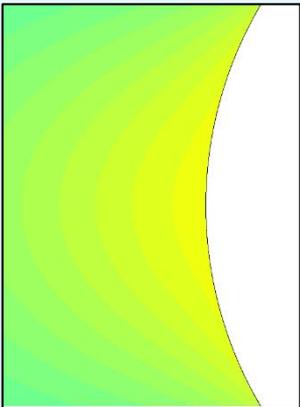
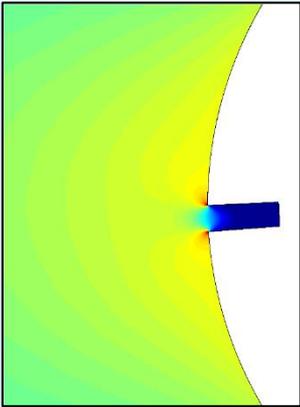


# Motivation

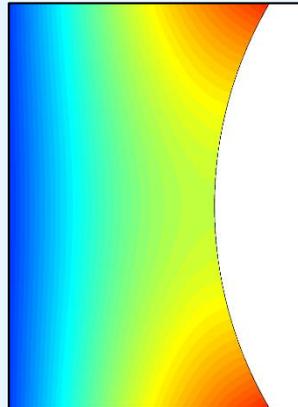
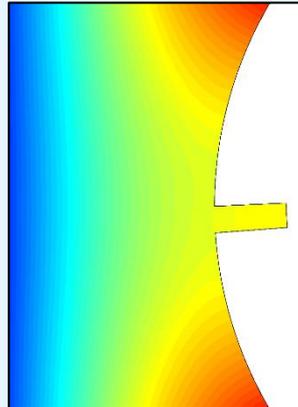
## ■ De-featuring

- A major drawback of the de-featuring is that is **dependent on the physics** of the problem or **even on the problem parameters!**

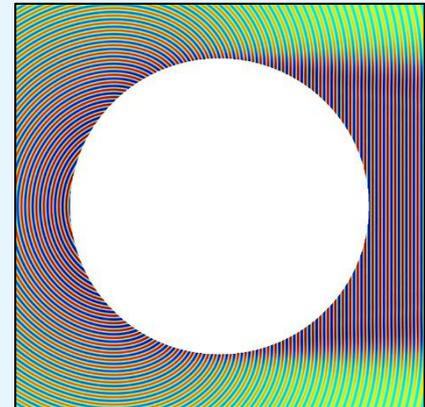
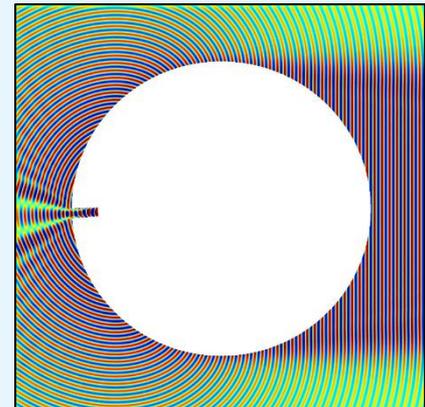
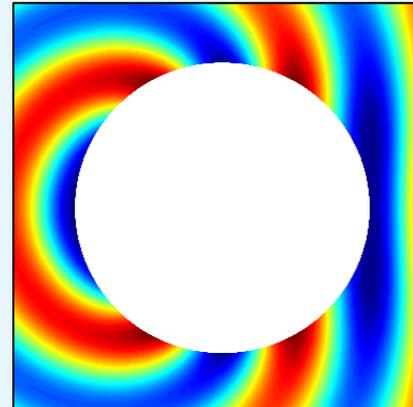
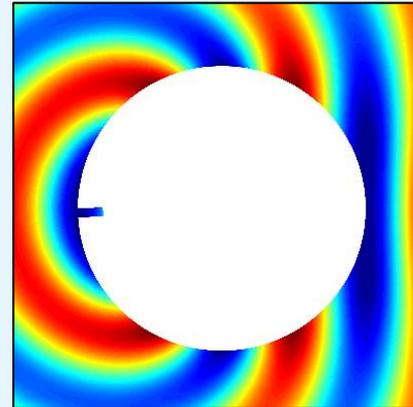
Solid mechanics



Heat transfer



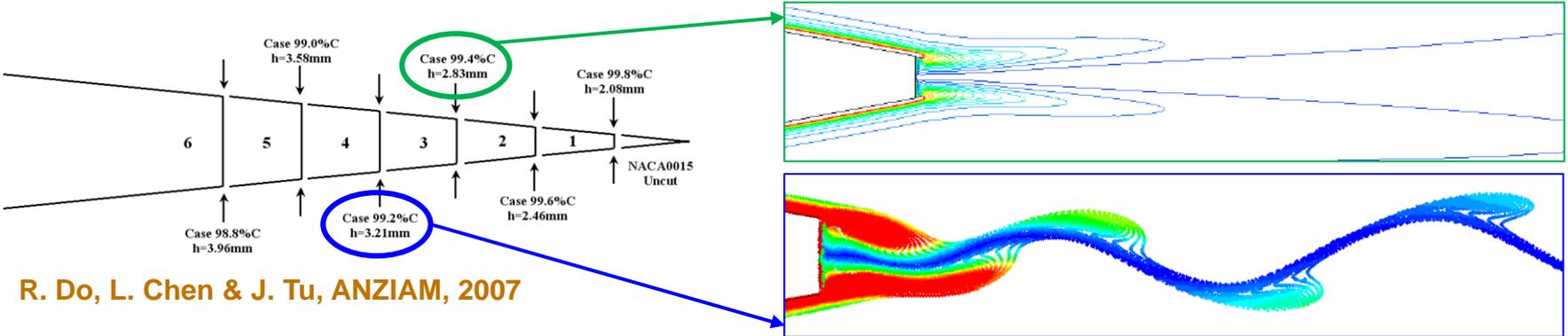
Electromagnetics / Acoustics



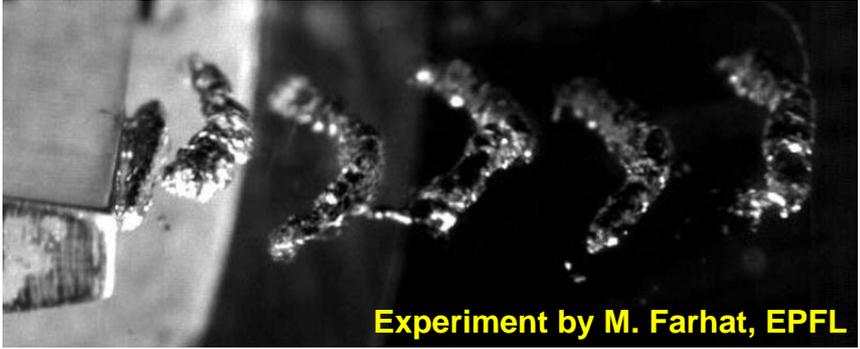
# Motivation

## De-featuring

- Blunt trailing edges crucial to accurately describe the physics (vortex shedding, vibrations, noise)

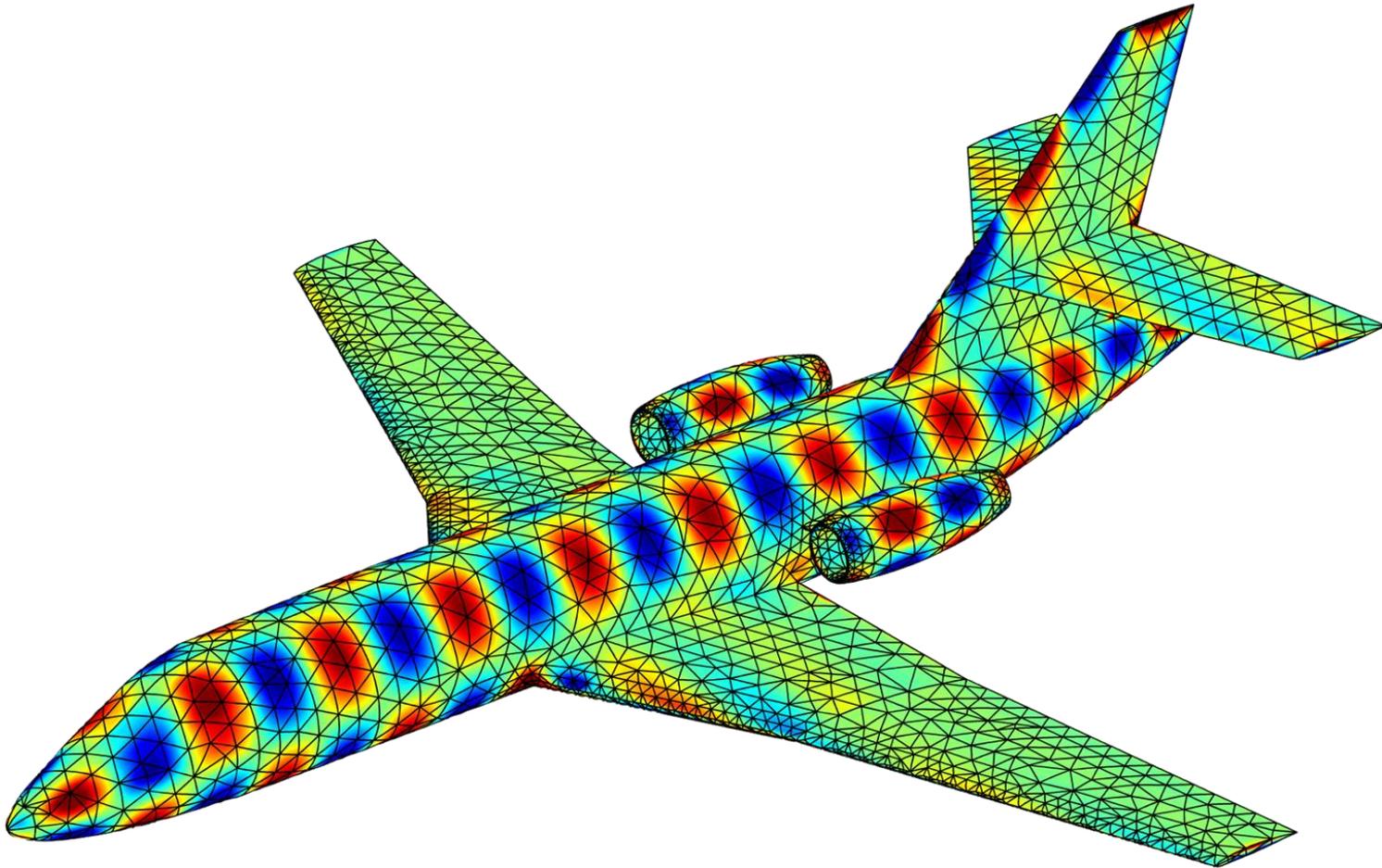


Case	Vortex Shedding	$f_s(Hz)$
99.8% <i>C</i>	No	-
99.6% <i>C</i>	No	-
99.4% <i>C</i>	No	-
99.2% <i>C</i>	Yes	137
99.0% <i>C</i>	Yes	128
98.8% <i>C</i>	Yes	113



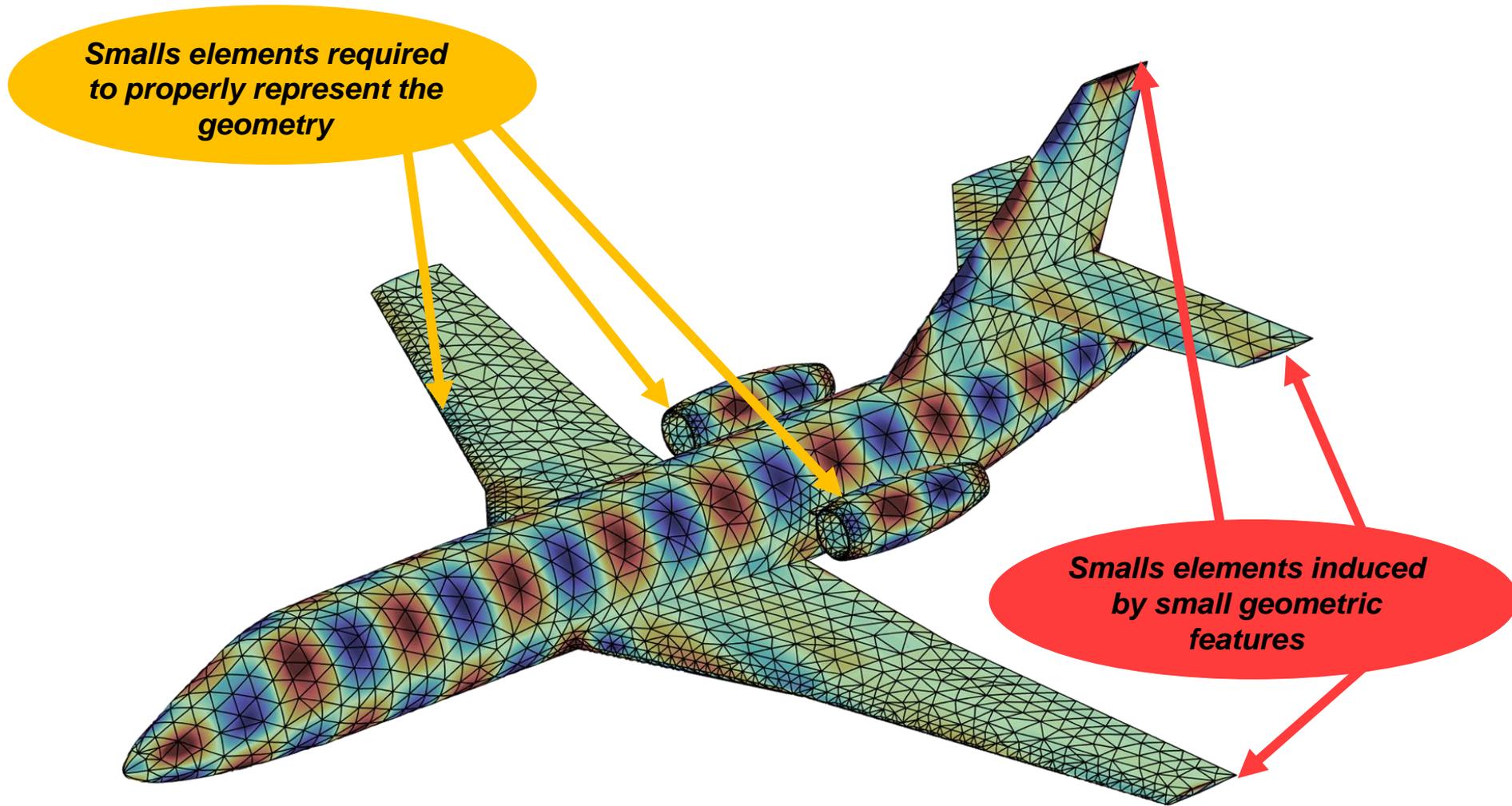
# Motivation

- The situation is even worse in a **high-order** context



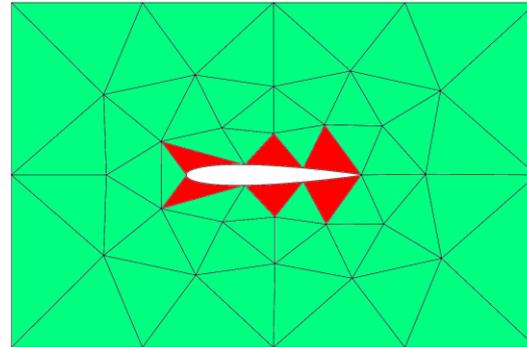
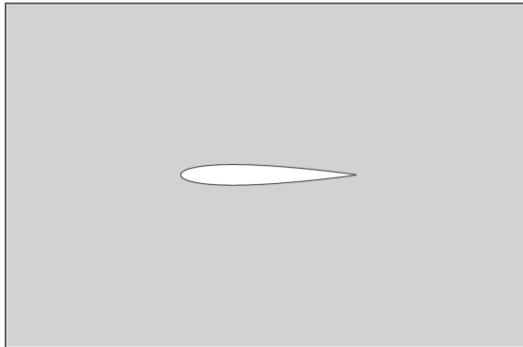
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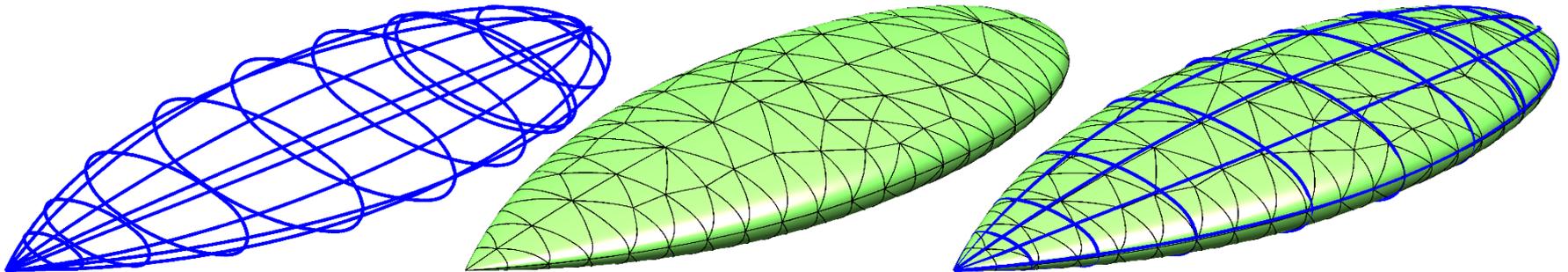


# NURBS-Enhanced Finite Element Method (NEFEM)

- Interior elements (straight edges/faces): standard FEs
- Curved elements (NURBS edges/faces): interpolation and integration with exact geometry description (overhead reduced to boundary elements)



- Spatial discretisation independent on the geometric definition



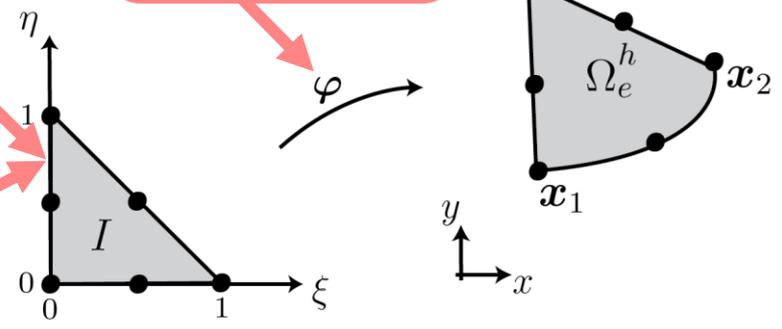
# NURBS-Enhanced Finite Element Method (NEFEM)

## Isoparametric FEM

Quadrature defined here

Polynomials defined here  
(i.e. **Jacobian of the mapping can severely affect your approximation properties**)

Isoparametric mapping  
(**polynomial**)

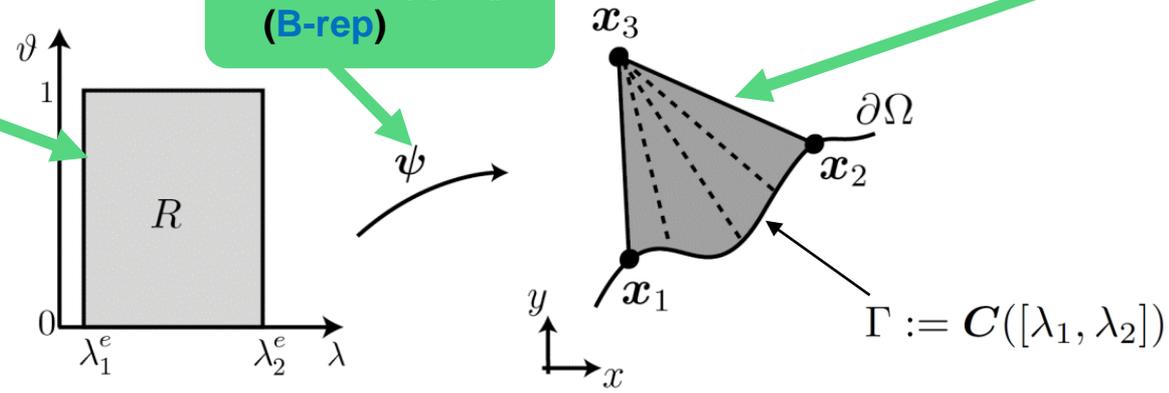


## NEFEM

Quadrature defined here

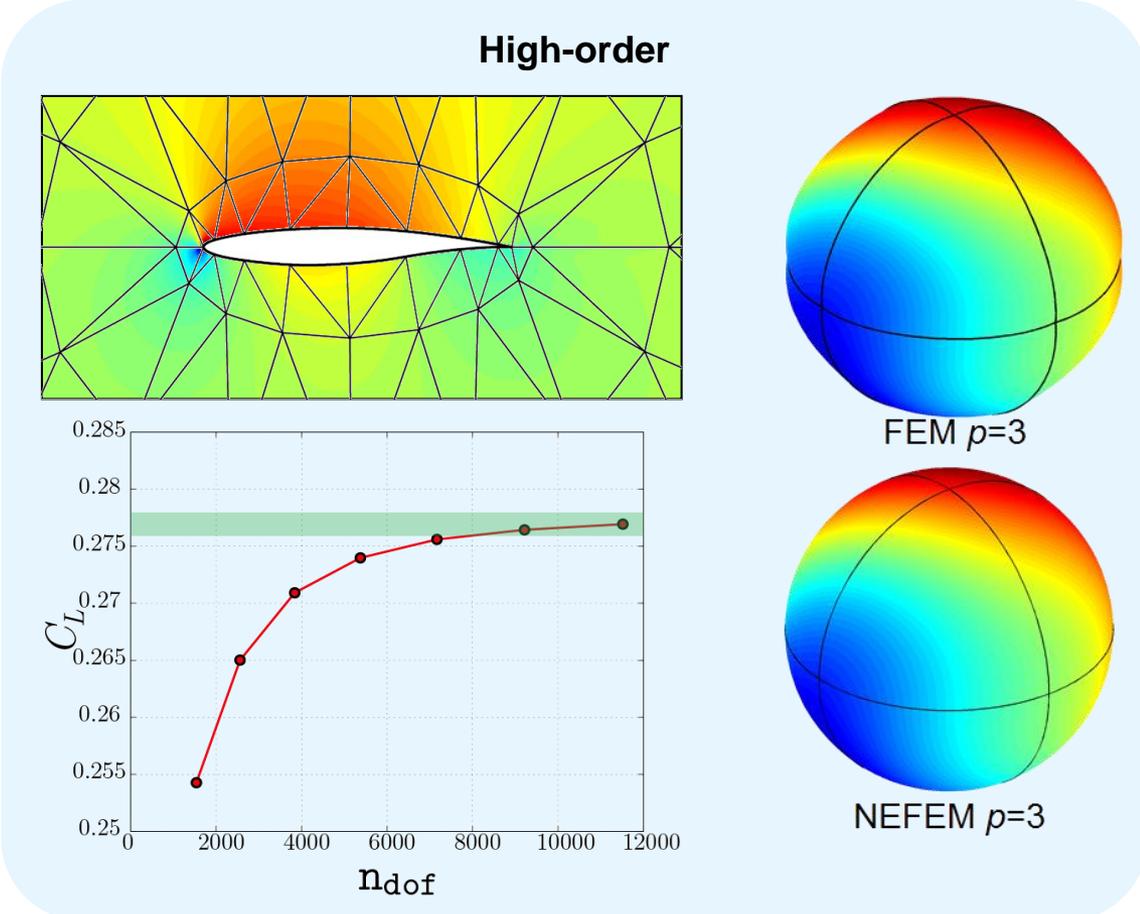
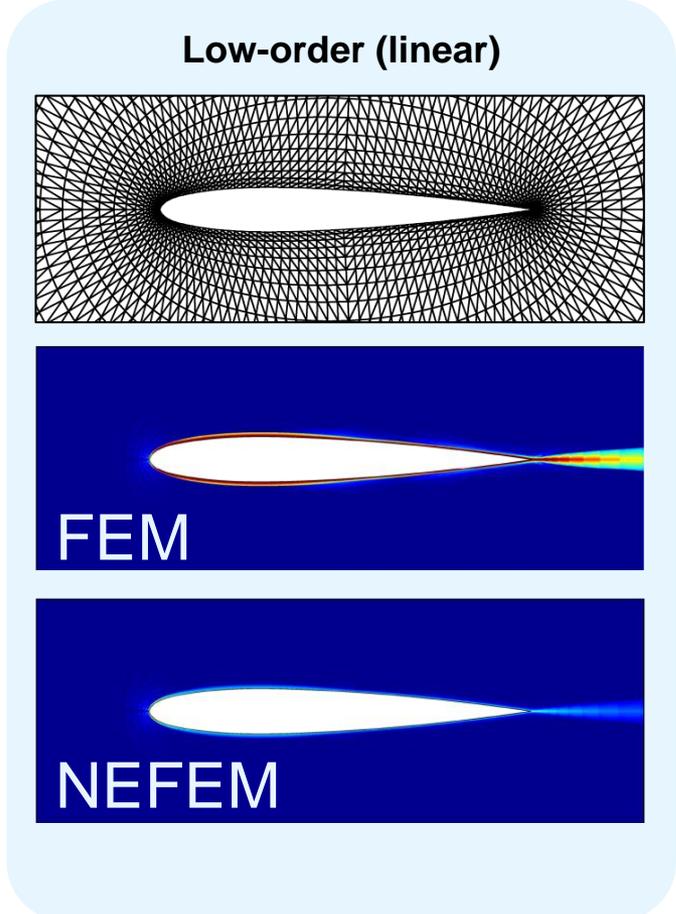
New mapping  
(**B-rep**)

Polynomials defined here  
(i.e. **NO mapping involved, better approximation properties**)



# NURBS-Enhanced Finite Element Method (NEFEM)

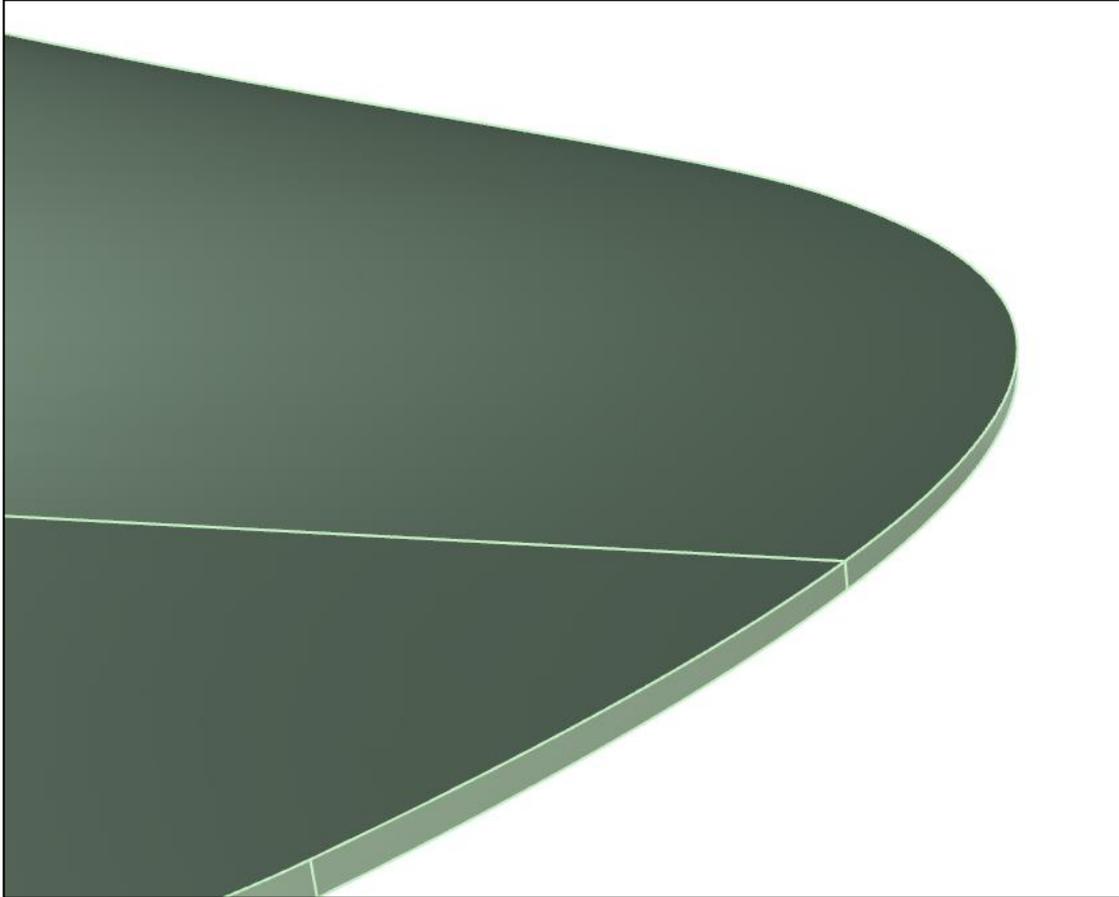
- Encapsulates the “exact” (CAD) boundary representation in the analysis stage. Advantages for both low and high-order



- Spatial discretisation independent on the geometric definition

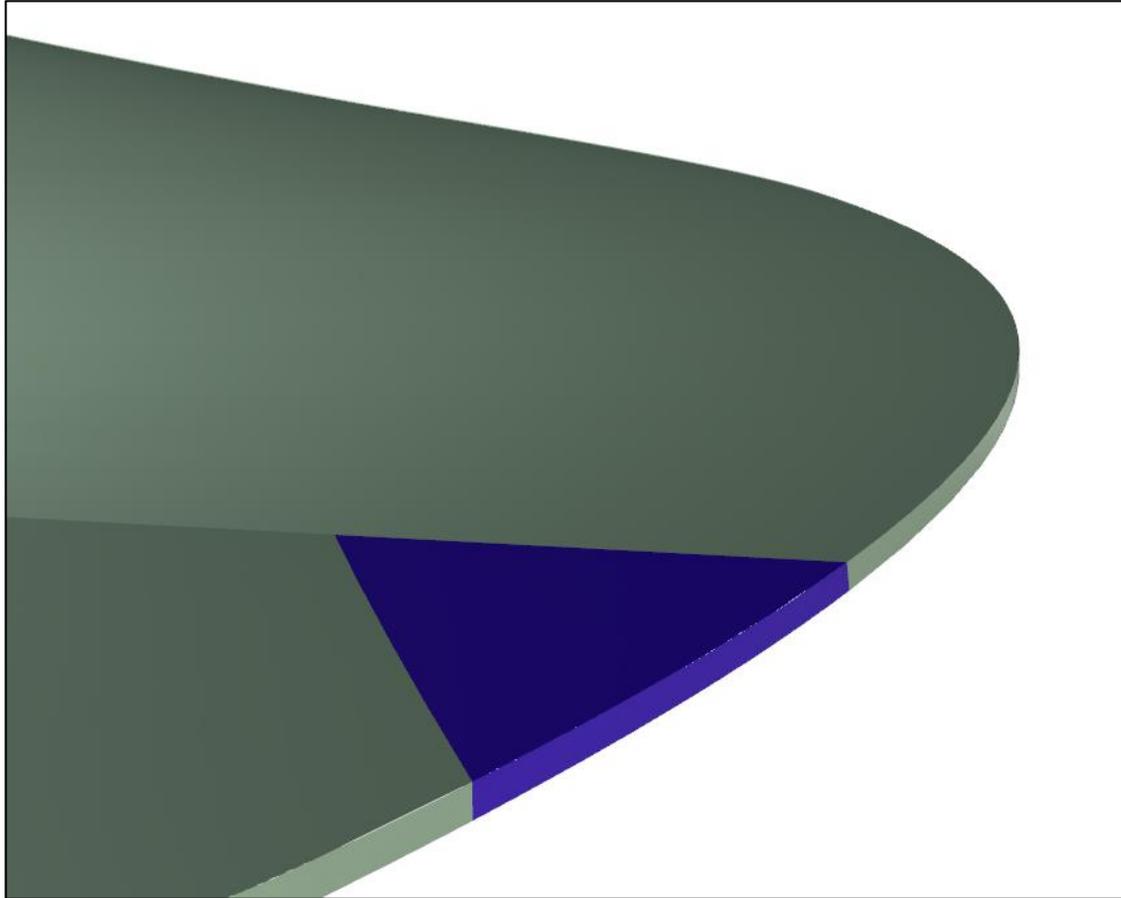
# NURBS-Enhanced Finite Element Method (NEFEM)

- De-featuring is no longer needed!



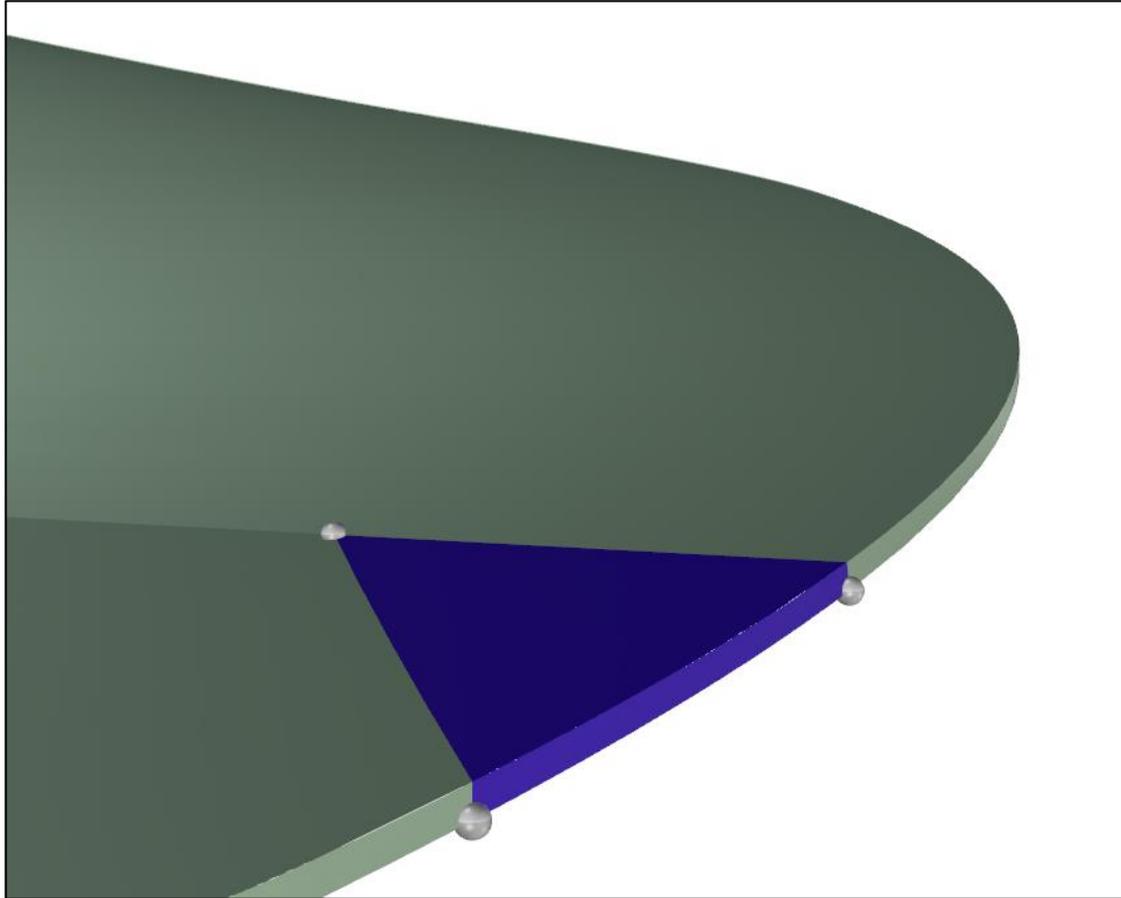
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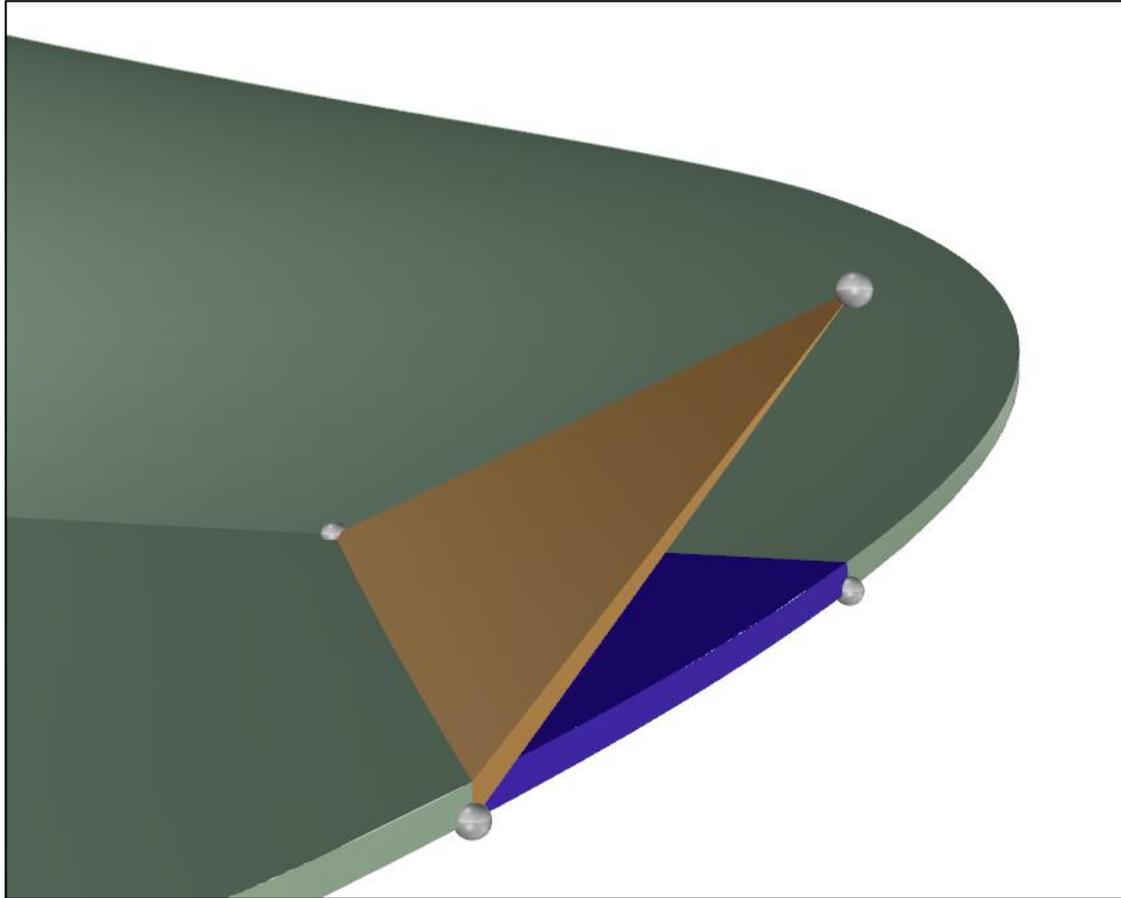
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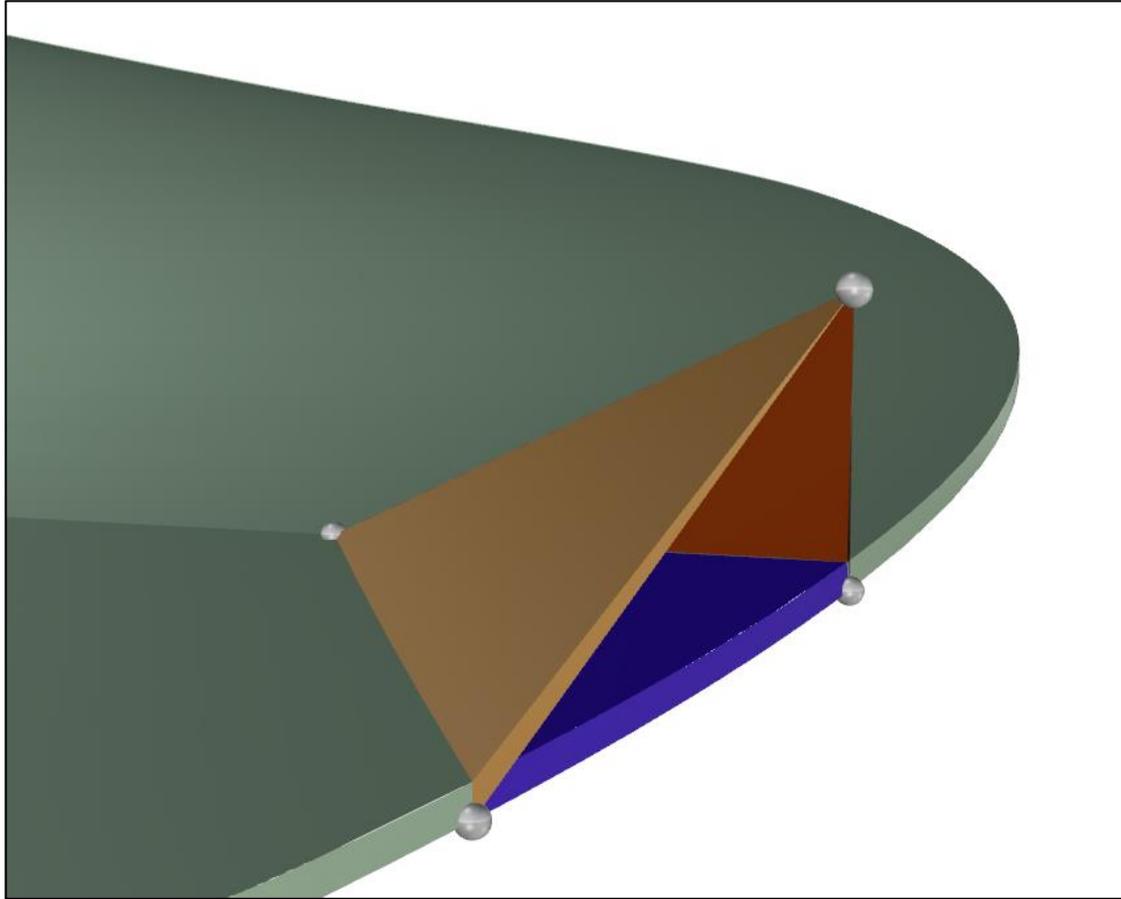
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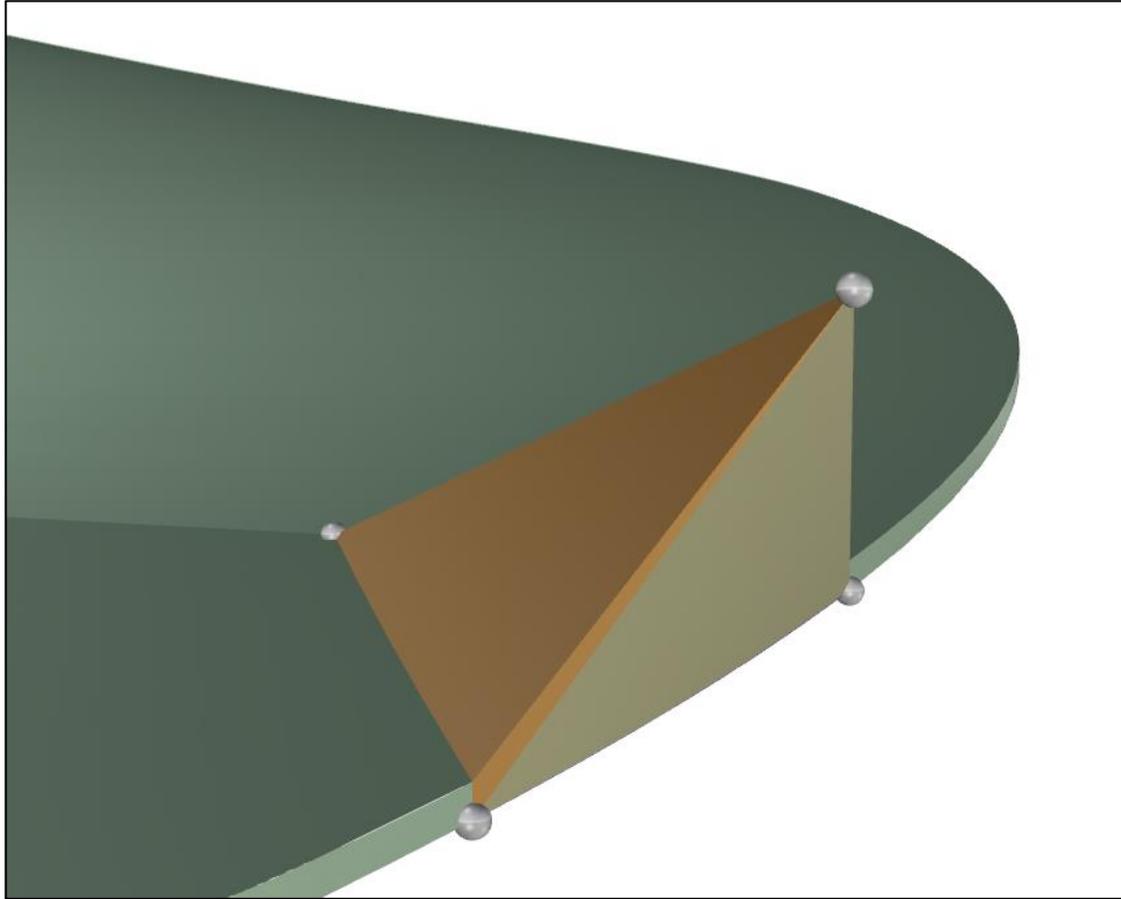
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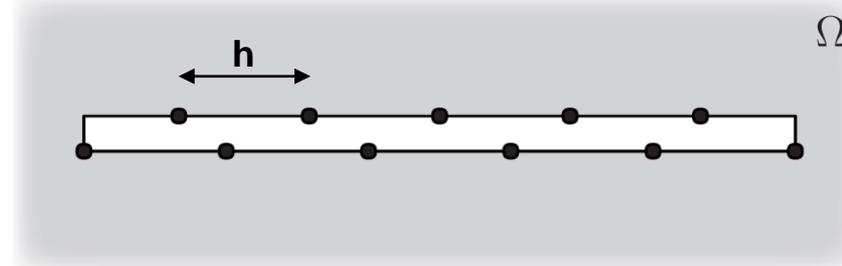
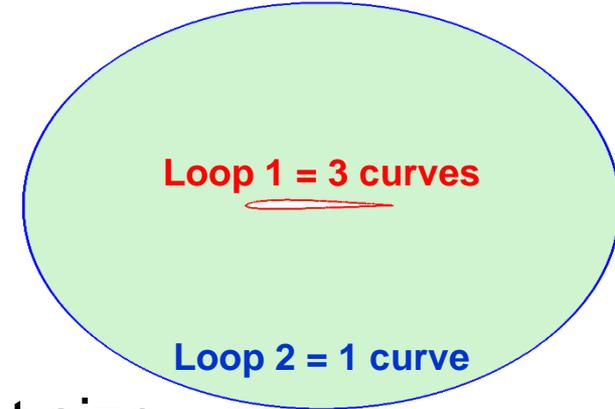
- De-featuring is no longer needed!



- But, how can we generate such meshes?

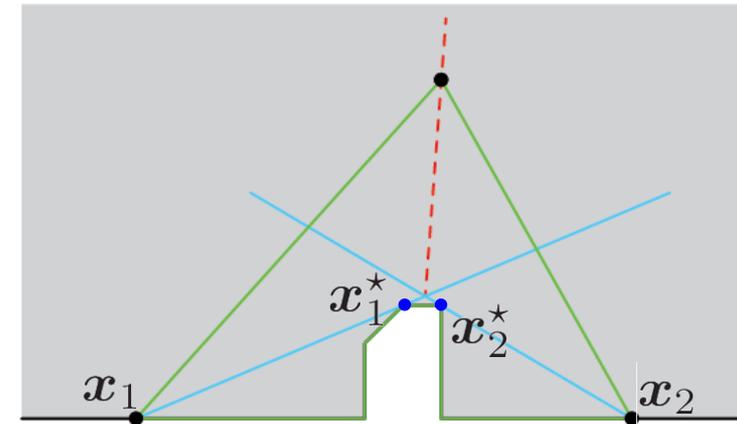
# Mesh generation – A priori approach

- **Boundary discretisation**
- Combine boundary curves into **loops**
- Discretise each loop with a desired element size



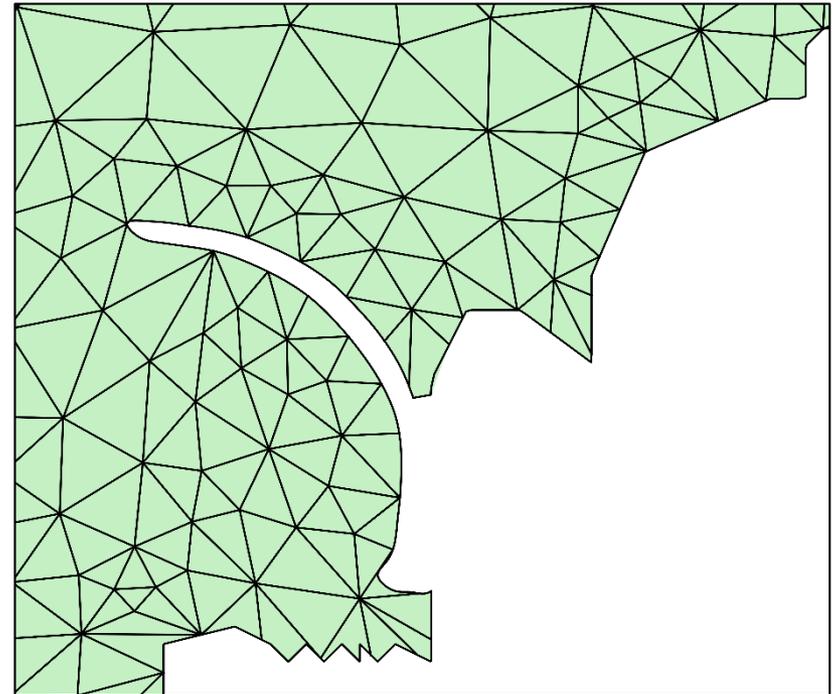
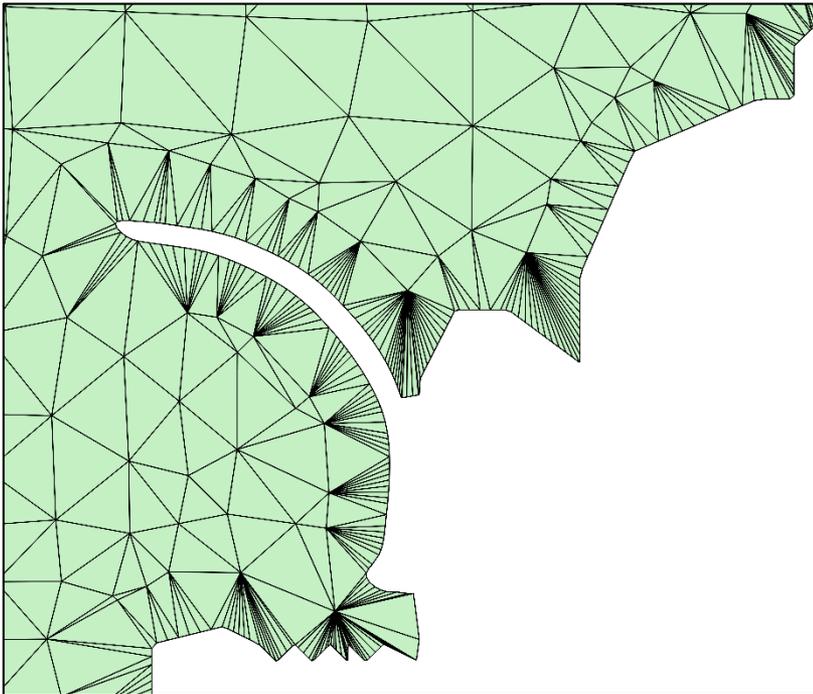
- **Volume discretisation**
- Define the **horizon** of each boundary node
- Look for a candidate interior node in the bisector of the two horizons

- Ensure visibility of boundary nodes from interior node
- Ensure interior edges with the required spacing



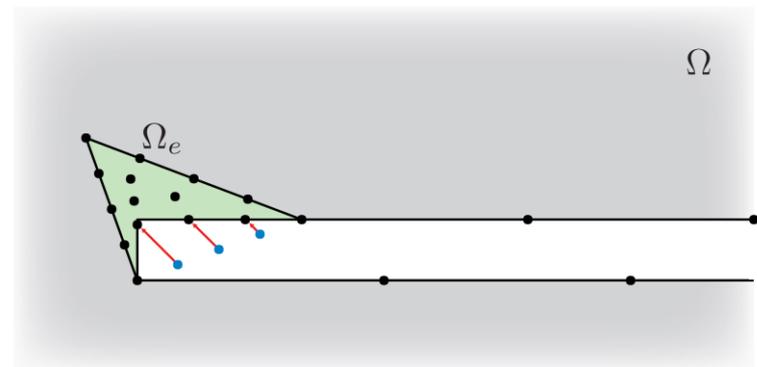
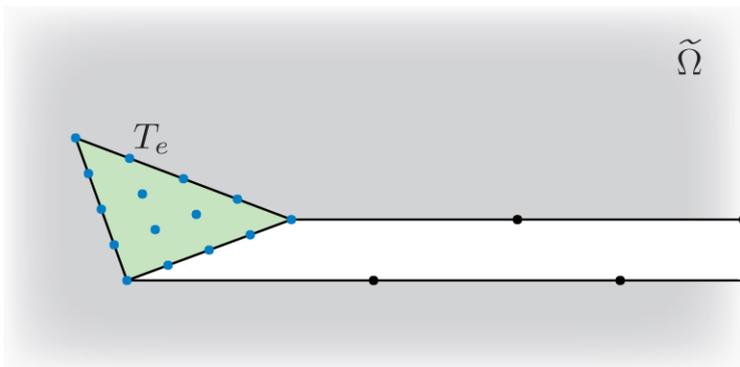
# Mesh generation – A posteriori approach

- Using a **standard mesh generator**
  - Create a mesh with the desired element size
- **Merge** elements to achieve the desired spacing
  - Collapse edge
- **Final cosmetics**



# Mesh generation – High-order

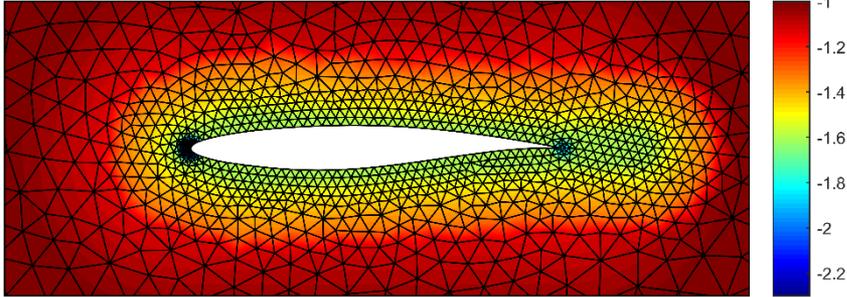
- **Element-by-element elastic analogy**
- Introduce **high-order nodal distributions** in each straight-sided element defined by its vertices
- Compute a **high-order boundary nodal distribution** over the **true geometry**. The new position of the boundary nodes is used to **imposed** the desired **displacement** on the boundary nodes
- On interior nodes impose zero displacement **IF** straight internal edges are desired
- Solve the elastic problem to find the **position of interior nodes**



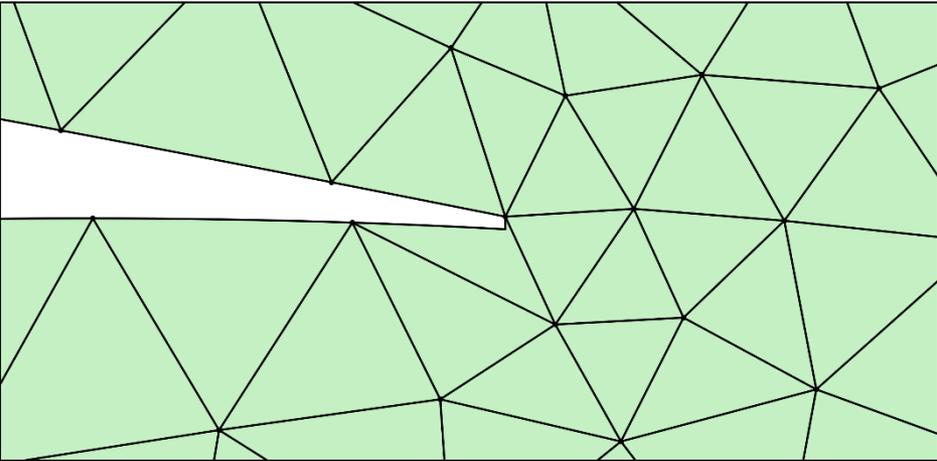
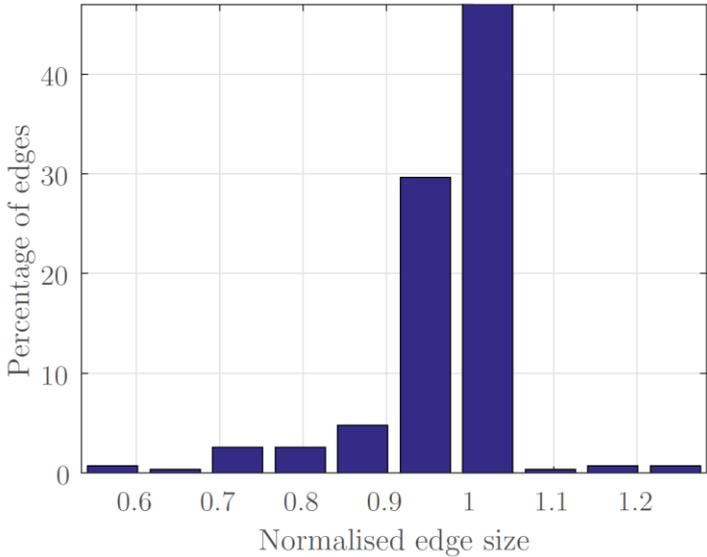
# Examples

- **Aerofoil with blunt trailing edge**

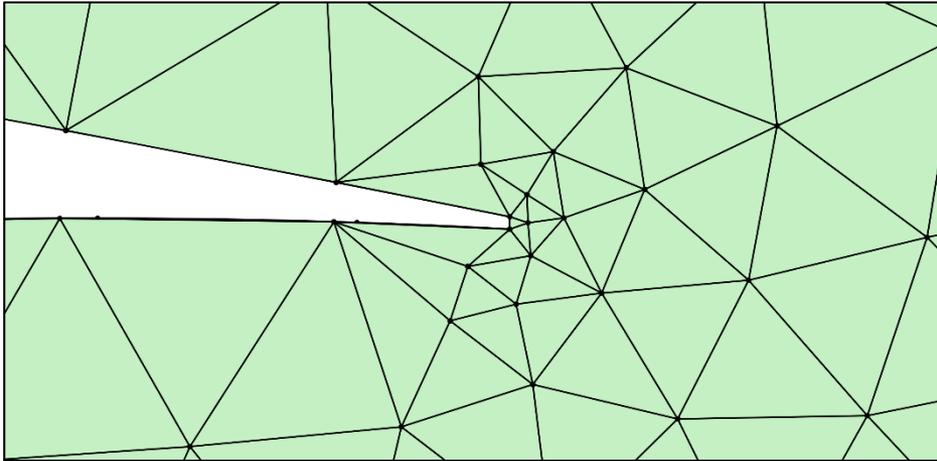
- Linear mesh with specified spacing



- Detailed view near the blunt trailing edge



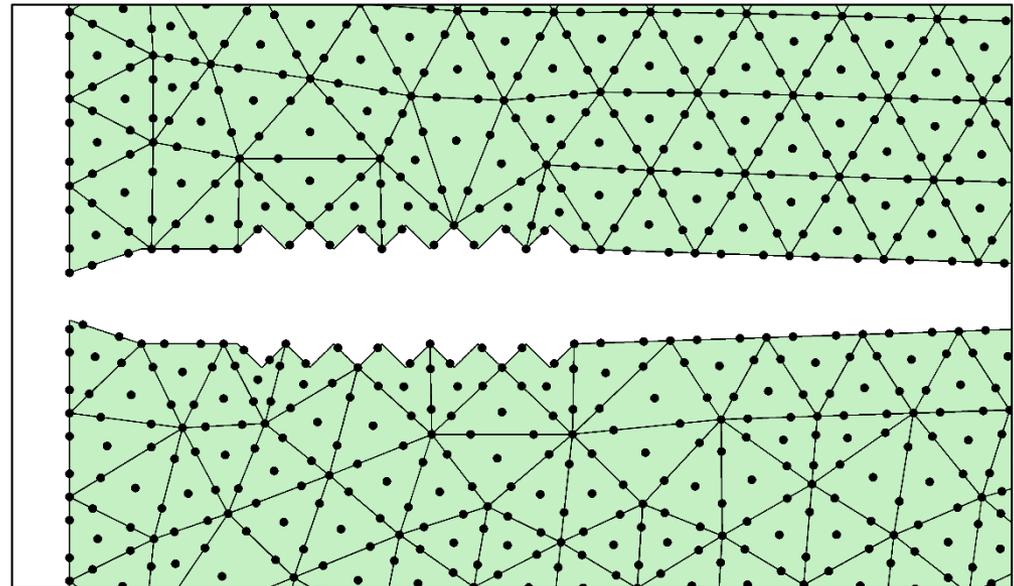
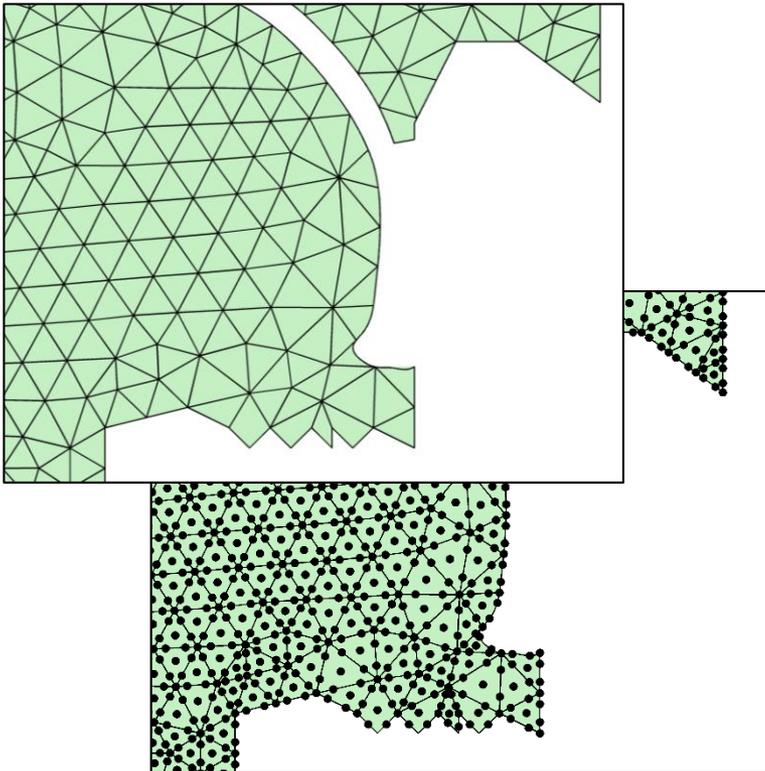
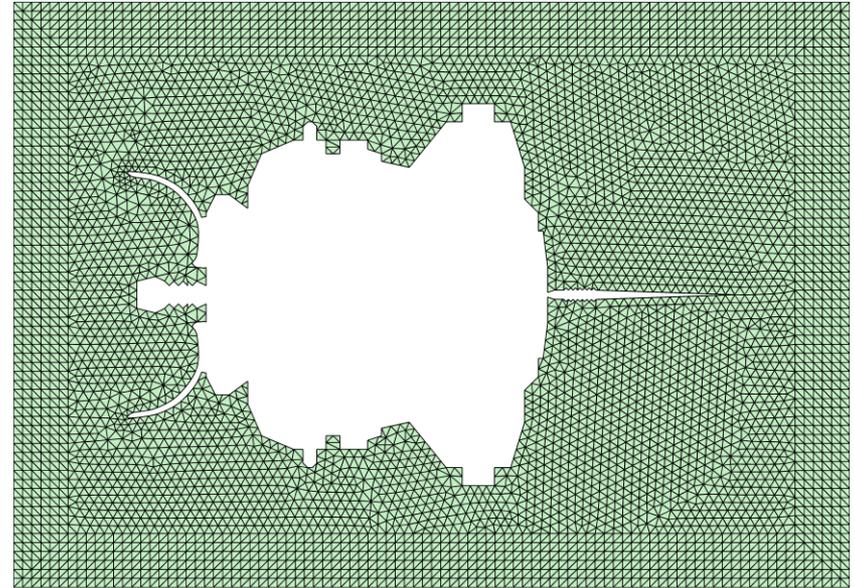
Proposed approach



Standard FEM mesh

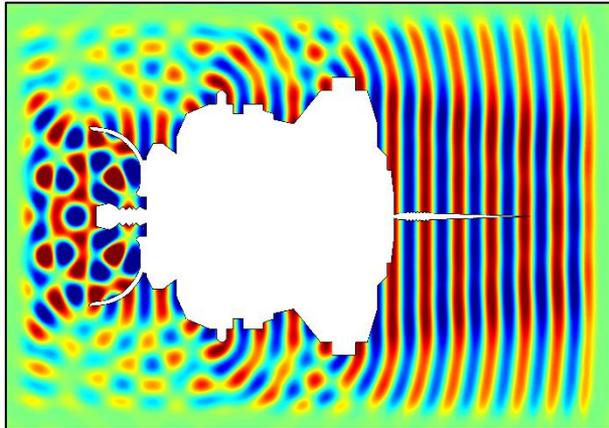
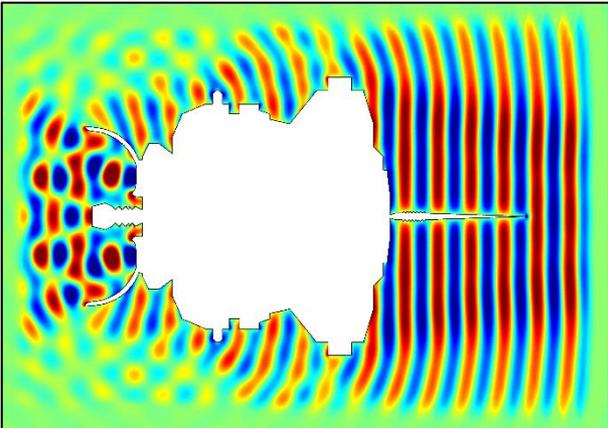
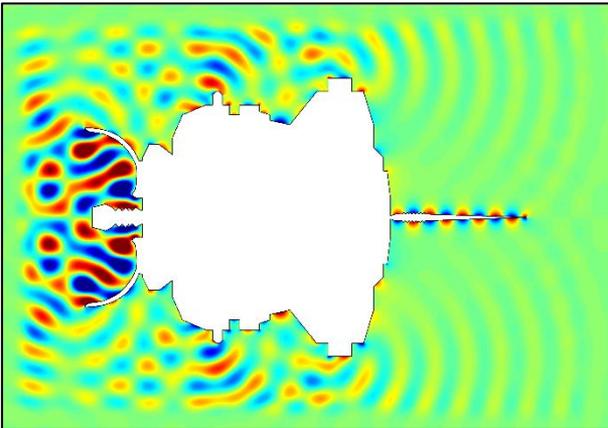
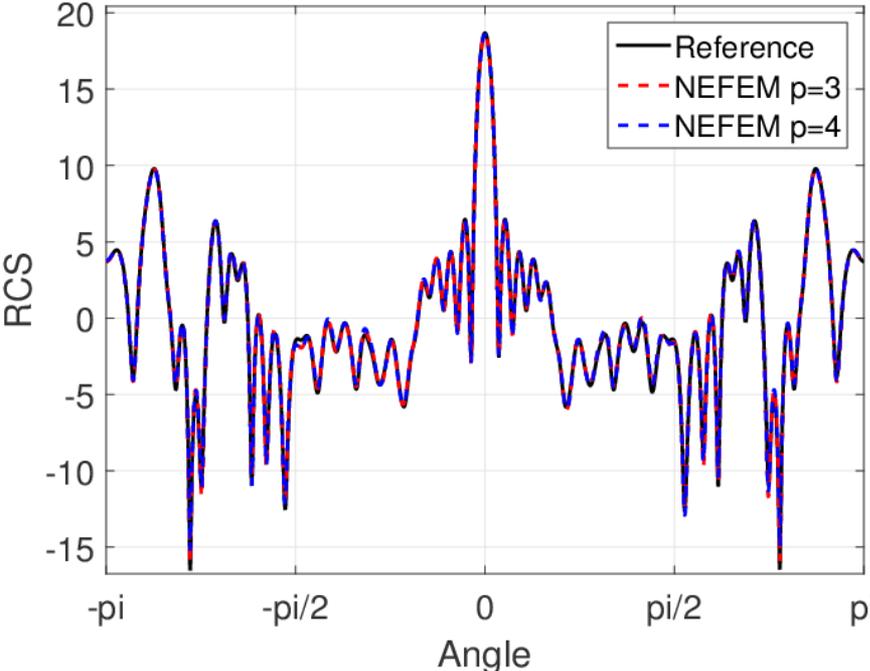
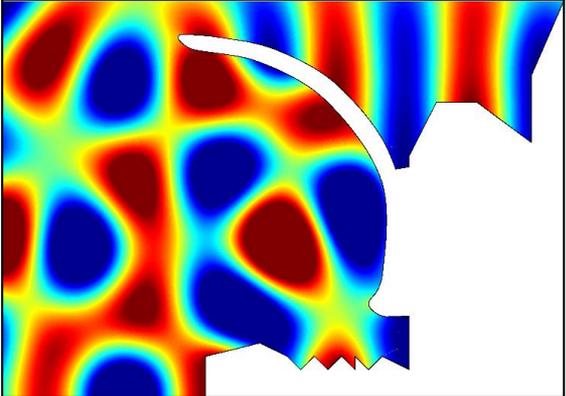
# Examples – Application to electromagnetic scattering

- **Satellite profile**
- Element size 3 times larger than the smallest feature
- 139 curves
- Details of the NEFEM mesh



# Examples – Application to electromagnetic scattering

- **Satellite profile**
- Scattered field and RCS



- Computation **140 times faster** with NEFEM and  $p=4$

# Ongoing work – 3D

## ■ 3D A posteriori approach

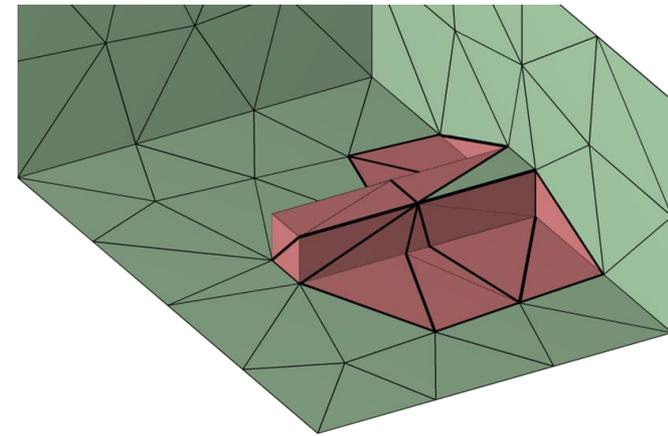
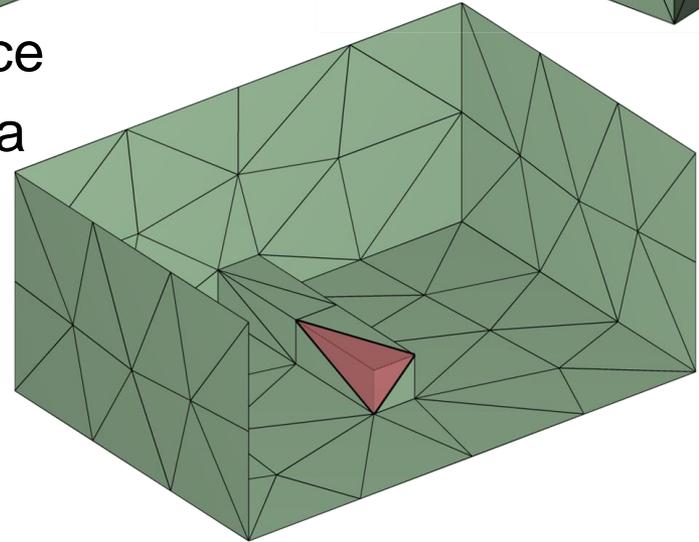
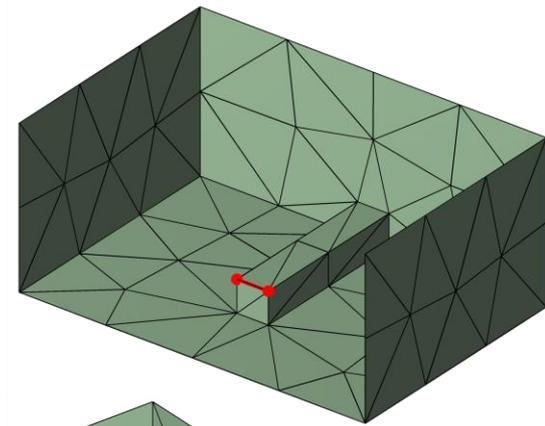
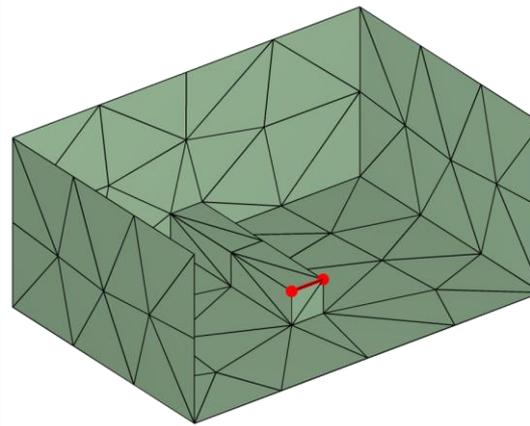
- Given a surface mesh
- Identify smallest edge
- Identify edge node with lower valence
- Edge collapse and remove zero area elements

## ■ The original mesh can be

- Linear
- High-order (curved)
- CAD compliant

## ■ Advantages

- CFL restriction
- Substantial reduction of elements



# Concluding remarks

- Development of a new and fully automatic mesh generation technique
  - Uses the CAD boundary representation of the domain
  - The element size is independent on the geometric complexity and on small geometric features
  - Circumvents the problem of de-featuring
- An a priori technique is based on
  - The boundary discretisation of loops instead of curves
  - A modified advancing front technique
- An a posteriori approach is based on merging
- Numerical examples demonstrate the applicability and potential of the proposed approach
  - Reduction of the total number of elements
  - Advantages when explicit time marching algorithms are used